Last Time: Proved every real, symmetric matrix has real eigenvalues. Lis End: Sow an example: we were able to diagonlize a motive "orthogonally". i.e. we found an orthogonal unter Q for mitex M and disgood D w/ M = QDQT ms Q orthgood =) QT = Q' So this is the some equation as M = PDP'.

Observations: DIF M is a motors and me can express M = QDQT for Q an orthogonal matrix and D a diagonal matrix, then (AB) = BTAT $M^T = (QDQ^T)^T = (Q^T)^TD^TQ^T = QD^TQ^T = QDQ^T = M.$ Hence if M is orthogonally diagonalizable, then M is symmetric !!

D M = QDQT for Q orthogonl and D diagonal, the Q=Q-1 implies M=QDQ-1, so Dis a intex of eignishes of M, and the columns of Q form bases for eigenspaces of M. Because Q is orthogonal, QTQ=I, so whenes of Q are mutually orthogonal; so eigenspines associated to different e-values

are orthogonal!

Point Mosthagonally diagonalizable implies: (1) M symmetric (2) the engenspres of M are motively orthogonal.

Miracolous: If M is symmetriz, then the eigenspaces of M one motivally orthogonal; hence M is orthogonally diagable.

Ex:
$$M = \begin{bmatrix} 0 & 1 & 1 \\ 1 & 1 & 1 \end{bmatrix}$$
 $P_{n}(\lambda) = ddt (M - \lambda I) = ddt \begin{bmatrix} 1 & 1 & 1 \\ 1 & 1 & 1 \end{bmatrix} + 1 ddt \begin{bmatrix} 1 & 1 & 1 \\ 1 & 1 & 1 \end{bmatrix}$
 $= -\lambda dt \begin{bmatrix} 1 & 1 & 1 \\ 1 & 1 & 1 \end{bmatrix} - 1 ddt \begin{bmatrix} 1 & 1 & 1 \\ 1 & 1 & 1 \end{bmatrix} + 1 ddt \begin{bmatrix} 1 & 1 & 1 \\ 1 & 1 & 1 \end{bmatrix}$
 $= -\lambda ((1 - \lambda)^{2} - 1) - ((1 - \lambda) - 1) + (1 - (1 - \lambda))$
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$$\lambda_{3} = 1 - 53; \quad V_{\lambda_{5}} = n \cdot \ln(M - \lambda_{7}) = n \cdot \ln\left[\frac{1}{1}, \frac{1}{1}, \frac{1}, \frac{1}{1}, \frac{$$

NB: We had distinct eigenvalues in this case. What if we didn't?

$$Ex: M = \begin{bmatrix} 4 & 1 & 2 \\ 2 & 4 & 4 \end{bmatrix}$$

$$P_{n}(X) = dxt (M - XI) = dxt \begin{bmatrix} 2 & 2 & 2 \\ 2 & 4 & 2 \end{bmatrix}$$

$$= (4 - X) dxt \begin{bmatrix} 4 - X & 2 \\ 2 & 4 - X \end{bmatrix} - 2 dxt \begin{bmatrix} 2 & 2 & 2 \\ 2 & 4 - X \end{bmatrix} + 2 dxt \begin{bmatrix} 2 & 4 - X \\ 2 & 2 & 2 \end{bmatrix}$$

$$= (4 - X) dxt \begin{bmatrix} 4 - X & 2 & 2 \\ 2 & 4 - X \end{bmatrix} - 4 dxt \begin{bmatrix} 2 & 4 - X \\ 2 & 4 - X \end{bmatrix}$$

$$= (4 - X) (4 - X)^{2} - 2^{2} - 4 (2(4 - X) - 2 \cdot 2)$$

$$= (4 - X) (4 - X - 2)(4 - X + 2) - 4 (2(4 - X - 2))$$

$$= (2 - X) (4 - X)(6 - X) - 8$$

$$= (2 - X) (24 - 10X + 1^{2} - 8)$$

$$= (2 - X) (X^{2} - 10X + 16) = (2 - X)(X - 2)(X - 8)$$

$$= (2 - X)^{2}(8 - X)$$

$$X_{1} = 2 : N. || (M - 21) = || N. || \begin{bmatrix} 2 & 2 & 2 \\ 2 & 2 & 2 \end{bmatrix} = || N. || \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}$$

$$\therefore \begin{bmatrix} 3 \\ 4 \end{bmatrix} \in V_{\lambda_{1}} \text{ iff } X + y + z = 0 \text{ iff } \begin{cases} x = -5 - t \\ 2 = t \end{cases} \therefore B_{\lambda_{1}} = \begin{bmatrix} -1 \\ 0 \end{bmatrix} \begin{bmatrix} -1 \\ 0 \end{bmatrix}$$

$$= || N. || \begin{bmatrix} 0 & 3 - 3 \\ 0 & -3 - 3 \end{bmatrix} = || N. || \begin{bmatrix} -1 & 1 & -2 \\ 0 & 0 & 0 \end{bmatrix}$$

$$\therefore \begin{bmatrix} 3 \\ 4 \end{bmatrix} \in V_{\lambda_{1}} \text{ iff } \begin{cases} x - 2 = 0 \text{ iff } \begin{cases} x = t \\ y = t \end{cases} \therefore B_{\lambda_{1}} = \begin{cases} -1 \\ 0 \end{bmatrix} \begin{bmatrix} -1 \\ 0 \end{bmatrix}$$

$$= || N. || \begin{bmatrix} 0 & 3 - 3 \\ 0 - 3 - 3 \end{bmatrix} = || N. || \begin{bmatrix} 1 & 0 & -1 \\ 0 & 0 & 0 \end{bmatrix}$$

$$\therefore \begin{bmatrix} 3 \\ 4 \end{bmatrix} \in V_{\lambda_{1}} \text{ iff } \begin{cases} x - 2 = 0 \text{ iff } \begin{cases} x = t \\ y = t \end{cases} \therefore B_{\lambda_{1}} = \begin{cases} -1 \\ 0 \end{bmatrix} \begin{bmatrix} -1 \\ 0 \end{bmatrix} \begin{cases} -1 \\ 0 \end{bmatrix}$$

$$= || N. || V_{\lambda_{1}} = V$$

NB: V, and V2 are both orthogonal to V3 (i.e. V, V3=0=V2·V3), but V, and Vz are not orthogenal to each other (inter V, vz=1 x 0). Fix: Apply GS-process to Bx: $|u_1 - v_1|$ $|u_2 - v_2 - \rho_{roj_{n_1}}(v_2)| = |v_2 - \frac{h_1 \cdot v_2}{u_1 \cdot u_1}|_{u_1 = \begin{bmatrix} -1 \\ 0 \end{bmatrix}} - \frac{1}{2} \begin{bmatrix} -1 \\ 0 \end{bmatrix} = \begin{bmatrix} -1/2 \\ -1/2 \end{bmatrix}$ $W_1 = \begin{bmatrix} -1 \\ 0 \end{bmatrix}, \quad W_2 = \begin{bmatrix} -1/2 \\ -1/2 \\ 1 \end{bmatrix}, \quad W_3 = \begin{bmatrix} 1 \\ 1 \end{bmatrix}.$ Filly: voralize u, uz, uz to obtain columns of Q: $|u_1| = \sqrt{2}$, $|u_2| = \sqrt{(\frac{1}{2})^2 + (\frac{1}{2})^2 + 1^2} = \sqrt{\frac{1+1+4}{4}} = \frac{1}{2}\sqrt{6}$, $|u_3| = \sqrt{3}$. Hence $W_1 = \frac{1}{52} \begin{bmatrix} -1 \\ 0 \end{bmatrix}$, $W_2 = \frac{2}{56} \begin{bmatrix} -1/2 \\ -1/2 \end{bmatrix}$, $W_3 = \frac{1}{53} \begin{bmatrix} 1 \\ 1 \end{bmatrix}$ Therefore: Q = [-1/2 -1/6 1/6] and D= [2 0 0]

[0 2/6 1/3]

[0 0 8] M=QDQT. "LE Salsing QT = QT and Theorem: Let M he a real matrix. The following are equivalent; (1) M is orthogonally diagonalizable. (2) M has it's eigenspaces mutually orthogonal. (3) R' has an orthonoral basis of eigenvectors of M. (4) M is Symmetric.

Thanks for your attention throughout this somester - Chris E